

Hyperplane Arrangements

V : n-dim \mathbb{C} -v.s.

$$X \subset V^* \setminus \{0\} \quad \bullet x \neq y \in X \Rightarrow x \text{ & } y \text{ not proportional.}$$

\uparrow
finite

$$X \text{ spans } V^*.$$

$$\nabla = d - \sum_{x \in X} \frac{dx}{x} t_x$$

$\nabla F = 0$ is the following system of PDEs:

- if $\{x_1, \dots, x_n\}$ is a basis of V^* ,

then $\forall x \in X, \quad x = \sum_{i=1}^n n_i(x) x_i$
 i.e. $dx = \sum_{i=1}^n n_i(x) dx_i$

Then

| |
|---|
| $\frac{\partial F}{\partial x_i} = \sum_{x \in X} \frac{n_i(x)}{x} t_x F \quad \forall i = 1, \dots, n$ |
|---|

Lemma (Kohnen) This system is consistent iff

$$\forall Y \subset X \text{ max'l s.t. } \text{Span}(Y) \text{ is } 2\text{-dim},$$

we have $\left[\sum_{y \in Y} t_y, t_z \right] = 0 \quad \forall z \in Y.$

Example 1 $V \cong \mathbb{C}^n$,

$$V \supset X = \{z_i - z_j \mid 1 \leq i < j \leq n\}$$

$$\left(\forall x \in X, H_x := \ker(x) \subset V \right)$$

$$H_{z_i - z_j} = \{(u_1, \dots, u_n) \in \mathbb{C}^n \mid u_i = u_j\}$$

$$V_{\text{reg}} = V \setminus \bigcup_{i < j} H_{z_i - z_j}$$

= configuration space of n points in \mathbb{C} (ordered)

• $Y \subset X$ max'l st $\dim(\text{Span } Y) = 2$.

$$Y = \{z_i - z_j, z_k - z_\ell\} \quad i, j, k, \ell \text{ distinct}$$

$$\{ z_i - z_j, z_j - z_k, z_i - z_k \}$$

Kohno's Lemma \rightsquigarrow rel^{ns}s for t_{ij} 's :

$$[t_{ij}, t_{ik}] = 0 ,$$

$$[t_{ij} + t_{jk} + t_{ik}, t_{ij}] = 0$$

or
 t_{jk}

or

t_{ik}

Example 2 V is 2 dim'l, $x, y \in V^*$ is basis

$$X = \{x, y, x+y\}$$

$$\nabla = d - \underbrace{\left(\frac{dx}{x} t_1 + \frac{dy}{y} t_2 + \frac{d(x+y)}{x+y} t_3 \right)}_{A}$$

$$dA = 0 \quad (\text{because } \frac{dx}{x} = d(\log x))$$

$$\begin{aligned} A \wedge A &= dx \wedge dy \left(\frac{t_1 t_2}{xy} + \frac{t_1 t_3}{x(x+y)} - \frac{t_2 t_1}{xy} - \frac{t_2 t_3}{y(x+y)} - \frac{t_3 t_1}{(x+y)x} + \frac{t_3 t_2}{(x+y)y} \right) \\ &= dx \wedge dy \left(\frac{[t_1, t_2]}{xy} + \frac{[t_1, t_3]}{x} - \frac{[t_2, t_3]}{y} \right) \end{aligned}$$

$$= dx \wedge dy \left(\frac{[t_1, t_2]}{xy} + \frac{[t_1, t_3]}{x(x+y)} - \frac{[t_2, t_3]}{y(x+y)} \right)$$

$$\mathcal{A} \wedge \mathcal{A} = 0 \Leftrightarrow (x+y)[t_1, t_2] + y[t_1, t_3] - x[t_2, t_3] = 0$$

Coeff of x : $[t_1, \overset{+t_2}{t_3}, t_2] = 0$

Coeff of y : $[t_1, t_2 + t_3] = 0$

$$\begin{matrix} \\ \\ +t_1 \end{matrix}$$

Proof of Kohno's Lemma:

$$\mathcal{A} = \sum_{x \in X} \frac{dx}{x} t_x \quad \text{To prove: } d\mathcal{A} - \mathcal{A} \wedge \mathcal{A} = 0$$

\Leftrightarrow (rank 2 commutation relations)

$d\mathcal{A} = 0$ in all cases (check!)

$$\mathcal{A} \wedge \mathcal{A} = 0 \Rightarrow x \mathcal{A} \wedge \mathcal{A} \Big|_{x=0} = 0$$

↑
(this is \Leftrightarrow)

$$\mathcal{A} \wedge \mathcal{A} = \frac{1}{2} \sum_{y_1, y_2 \in X} \frac{dy_1 \wedge dy_2}{y_1 y_2} [t_{y_1}, t_{y_2}]$$

$$x \mathcal{A} \wedge \mathcal{A} \Big|_{x=0} = dx \wedge \sum_{y \in X} \frac{dy}{y} \Big|_{x=0} [t_x, t_y]$$

• $X \setminus \{x\}$ equivalence rel^x

$y_1 \sim y_2$ if $y_1|_{x=0}$ is prop. to $y_2|_{x=0}$

i.e. if $\begin{cases} y_1 \in \text{Span}\{x, y_2\} \\ y_2 \in \text{Span}\{x, y_1\} \end{cases}$

• $X \setminus \{x\} = X_1 \cup \dots \cup X_k$ } (equivalence classes)

$$\frac{dy_1}{y_1}|_{x=0} = \frac{dy_2}{y_2}|_{x=0}$$

& x, span
2 dim^e space

$$x A_1 A|_{x=0} = \sum_{j=1}^k \frac{dx \wedge dy_j}{y_j}|_{x=0} \left[t_x, \sum_{y \in X_j} t_y \right] = 0$$

$$\Leftrightarrow \left[t_x, \sum_{y \in X_j} t_y \right] = 0 .$$

□

Example $t_{ij} = \text{transposition } (i \ j) \quad (1 \leq i, j \leq n, i \neq j)$

$$[t_{ij}, t_{ke}] = 0, [t_{ij} + t_{jk} + t_{ik}, t_{ik}] = 0$$

\rightsquigarrow a consistent system on $\mathbb{Y}_n(\mathbb{C}) = \mathbb{C}^n \setminus \text{diagonals}$

$$\nabla = d - \sum_{1 \leq i < j \leq n} \frac{d(z_i - z_j)}{z_i - z_j} \quad (i, j)$$

Root Systems (as examples of hyperplane arrangements).

(trigonometric analogue of Kohno's lemma? only for root systems)

Let E be a real (finite-dim) vector space

together w/ a positive definite, symmetric, bilinear form:

$$(\cdot, \cdot) : E^2 \rightarrow \mathbb{R}.$$

. use it to identify $E^* \xrightarrow{\sim} E$

$$(v(\alpha), \phi) = \alpha(\phi) \quad \forall \alpha \in E^*, \phi \in E.$$

. For every $\alpha \in E^*$, $\alpha \neq 0$, we have a linear map

$$S_\alpha : E \rightarrow E$$

$$\phi \mapsto \phi - \frac{2\alpha(\phi)}{(\alpha, \alpha)} v(\alpha) \quad (\text{reflection in } \text{Ker } \alpha)$$

$$S_\alpha : E^* \rightarrow E^*$$

$$\gamma \mapsto \gamma - \frac{2(\gamma, \alpha)}{(\alpha, \alpha)} \cdot \alpha$$

$$S_\alpha(\gamma) = \gamma \quad \forall \gamma \text{ s.t. } (\gamma, \alpha) = 0$$

$$S_\alpha(\alpha) = -\alpha$$

$$S_\alpha^2 = \text{id}$$

Defn A root system is a finite set of nonzero elements of E^* : $R \subset E^* \setminus \{0\}$ (finite) s.t

$$(1) \quad \alpha, \beta \in R; \quad \alpha = c\beta \Rightarrow c = \pm 1$$

$$(2) \quad R \text{ spans } E^*$$

$$(3) \quad (\text{integrality}) \cdot \alpha, \beta \in R \Rightarrow \frac{2(\alpha, \beta)}{(\alpha, \alpha)} \in \mathbb{Z}$$

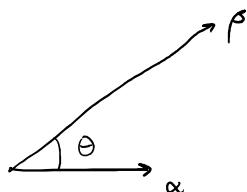
$$(4) \quad \forall \alpha \in R, \quad S_\alpha(R) \subset R$$

Examples in 2D

Pick $\alpha, \beta \in R$ s.t. \angle_{α}^{β} is acute (use (4))

$$|\beta| \geq |\alpha|$$

$$|\beta| = r \geq 1$$



$$|\alpha|=1$$

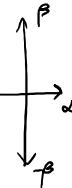
Integrality: $2r \cos \theta \in \mathbb{Z}$?
 $2, \dots \rightarrow \{ 4 \cos^2 \theta \in \mathbb{Z} \}$

$$\text{Integrality: } \begin{cases} 2r \cos \theta \in \mathbb{Z} \\ 2/r \cos \theta \in \mathbb{Z} \end{cases} \quad \left\{ \begin{array}{l} 4 \cos^2 \theta \in \mathbb{Z}_{\geq 0} \\ 4 \cos^2 \theta \in \mathbb{Z} \end{array} \right.$$

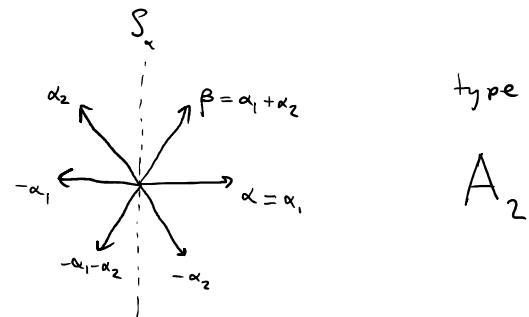
$4 \cos^2 \theta = 0, 1, 2, 3, \dots$ or ~~(not proportional)~~

$\alpha \nparallel \beta \text{ not proportional}$

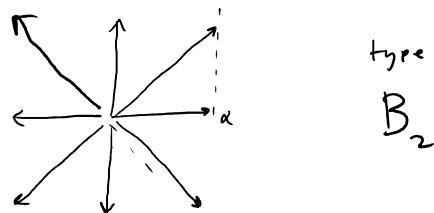
$$4 \cos^2 \theta = 0 : \theta = \frac{\pi}{2} \Rightarrow \text{root system = reducible.}$$



$$4 \cos^2 \theta = 1 : \cos \theta = \frac{1}{2}, \theta = \frac{\pi}{3} \Rightarrow r=1 :$$



$$4 \cos^2 \theta = 2 : \cos \theta = \frac{1}{\sqrt{2}}, \theta = \frac{\pi}{4} \Rightarrow r=\sqrt{2}$$



Last case: $r=\sqrt{3}, \theta = \frac{\pi}{6}, \dots$