Theorem Let U be an open set in \mathbb{R}^n , $f: U \to \mathbb{R}$ is of class C^{mri} on U. Then for any $\vec{a} \in U$, $\lim_{k \to \delta} \frac{|f(\vec{a} + \vec{u}) - \sum_{|\vec{u}| \in m} \frac{1}{|\vec{u}|} \frac{2f(\vec{a}) \vec{h}_{\vec{u}}|}{|\vec{h}|^m} = 0$

 $f(\vec{a} + \vec{h}) = \sum_{\vec{k} \in \mathbf{m}} J_{z} f(\vec{a}) /_{|\vec{k}|} \qquad h_{f} + |\vec{h}|^{\mathbf{m}} f_{\mathbf{m}}(\vec{h}) \qquad \text{where } \lim_{\vec{h} \to \vec{0}} f_{\mathbf{m}}(\vec{h}) = 0.$

Proof Strategy: reduce to single-vor case.

Proof: Choose r>0 So $\overline{B(r, \check{a})} \subseteq (I \cdot (hoose \ \check{h} \in B(r, \check{o}) \setminus \{\check{o}\})$ $g_{\check{o}, \check{h}}(t) = f(\check{a} + t\check{h}), \quad t \in (-\frac{r}{|h|}, \frac{r}{|h|})^{n}$

Lemma 2: for $0 \le k \le m+1$, $g_{z,k}^{(k)}(t) = \sum_{|I| \le k} \beta_I f(\vec{a} + t\vec{h}) \vec{h}_{I}$

Proof , flemaz: Induction on k.

 $\begin{aligned} & k=0 \; ; \quad j(\vec{\alpha},\vec{h})(t) = f(\vec{\alpha}+t\vec{h}) \quad \text{twe by def.} \\ & \text{Inov}(\vec{\epsilon}(\vec{\alpha})) = \frac{1}{2} \int_{t} g_{\vec{k},\vec{k}}(t) = \int_{t}^{t} \left(\sum_{j \in K} g_{j}f(\vec{\alpha}+t\vec{h})\vec{h}_{j}\right) \\ & = \sum_{|\vec{l}| \in K} \frac{1}{2} \int_{t}^{t} f(\vec{\alpha}+t\vec{h}) \int_{t}^{t} f(\vec{n}+t\vec{h}) \int_{t}^{t} f(\vec{n}+t\vec{h}) \int_{t}^{t} f(\vec{n}+t\vec{h}) \int_{t}^{t} f(\vec{n}+t\vec{h}) \int_{t}^{t} f(\vec{n}+t\vec{h}) \int_{t}^{t} f(\vec{n}+t\vec{h}) \int_{t}^{t} f(\vec{n}+t$

= Z J f(Z+t] T

So by movetion it is tree.

back to theorem proof:

by single variable taylor theorem:

remember term

$$g_{\vec{a},\vec{k}}(t) = \sum_{k=0}^{m} \frac{1}{k!} g_{\vec{c}k}^{(k)}(0) t^{k} + R(t)$$

$$f_{\vec{a},\vec{k}}(1) = \sum_{k=0}^{m} \frac{1}{k!} \sum_{k \in \mathbb{Z}} j_{\vec{a}} f(\vec{a} + \vec{h}) \vec{h}_{\vec{a}} + R(1)$$

$$= \sum_{|\vec{a}| \in \mathbb{Z}} \frac{1}{|\vec{a}|} \partial_{\vec{b}} f(\vec{a} + \vec{h}) \vec{h}_{\vec{b}} + R(1)$$

$$\frac{\left|f(\vec{a}+\vec{h})-\sum_{\substack{l\neq l\leq m}}\frac{1}{|t|!}\partial_{\mathbf{I}}f(\vec{a}+\vec{h})\vec{h}_{\mathbf{I}}\right|=\left|R(i)\right|}{\left|\vec{h}\right|^{m}}$$

So It reduces to snowing $\lim_{n\to \bar{0}} \frac{|R(1)|}{|h|^m} = c$

myrange form of R(t):

$$R(t) = \frac{g_{\vec{a},\vec{h}}^{(m+1)}(c)}{(m+1)!} t^{mn} \quad \text{where } c \text{ btun } 6 \text{ and } t.$$

$$R(1) = \sum_{\underline{\text{ISISM+1}}} \gamma_{\underline{I}} f(\underline{\alpha} + \overline{c}h) \overline{h}_{\underline{I}}$$
 where $C \in (0, 1)$.

ät Ch & B(r, x) Which is a compact set, so by EVT | g f (a + ch) | = M1 which is maximal value be of compactness.

$$|\vec{h}_1| = |h_{i_1}| |h_{i_2}| \cdots |h_{i_{m_i}}| \leq |\vec{h}|^{m+1}$$

$$\leq R(1) \leq M_{1} |\mathcal{C}|_{m+1}$$

f: U > R have a local meximum or minimum at ach if f hus a maximum or minimum at a when restricted to B(V, a) forsone roo.

Clearly! If f has a local max/min at a tuen of has a local max/min when restricted to a like in any coordinate direction. \Rightarrow dif(a)=0 for i=1,-,n \Rightarrow $\nabla A^{2}=0$.

Definition f: U -> R have a without point at a EU if THA

Definition f: U -> R has a witical point at a & U if D+(a) =0.

This is a necessary but not sufficient condition for being a local markenin.

Additional Complication: at a critical point, of continue local maximum resome directions & cocal minimum on other directions. In that any we say of here a suddle point at a.

Example: f(x,14)= x2-y2 a pringle (200)

To analyze whether we have a local mex/min or shadle at critil, we med 2nd dawative test

at a critical point \vec{a} , me Second order they for expansion looks like $f(\vec{a}+\vec{b}) = f(\vec{a}) + O + \frac{1}{z} \sum_{i,j=1}^{n} 2i l_i f(\vec{a}) \text{ high}_{j} + |\vec{b}|^{2z} (\vec{b})$.

Definition let $A = (a_{ij})$ non symmetric matrix (i.e. $a_{ij} = a_{ji}$).

Then Quadratic form associated to A is:

 $Q_A(\vec{x}) = \sum_{i,j=1}^n \alpha_{ij} \chi_i \chi_j$

We say that Q_A is positive definite if $Q_A(\vec{x}) > 0$ $\forall \vec{x} \neq 0$ negative definite $Q_A(\vec{x}) < 0$ $\forall \vec{x} \neq 0$ in definite if $Q_A(\vec{x}) < 0$ $\forall \vec{x} \neq 0$ Degenerate if $Q_A(\vec{x}_0) > 0$