

Differentiability of $\mathbb{R}^n \rightarrow \mathbb{R}^m$

Proposition: Let $U \subseteq \mathbb{R}^n$ open. Then f is differentiable at \vec{x}_0 iff there is a function $\varepsilon: B(r, \vec{0}) \rightarrow \mathbb{R}$ defined on some ball of small enough radius r such that $\forall \vec{h} \in B(r, \vec{0})$ we have $f(\vec{x}_0 + \vec{h}) = f(\vec{x}_0) + \nabla f(\vec{x}_0) \cdot \vec{h} + |\vec{h}| \varepsilon(\vec{h})$ with $\lim_{\vec{h} \rightarrow \vec{0}} \varepsilon(\vec{h}) = 0$

Proof:
$$\varepsilon(\vec{h}) = \begin{cases} \frac{f(\vec{x}_0 + \vec{h}) - f(\vec{x}_0) - \nabla f(\vec{x}_0) \cdot \vec{h}}{|\vec{h}|} & \vec{h} \neq \vec{0} \\ 0 & \vec{h} = \vec{0} \end{cases}$$

Want to extend the notion of differentiability to vector-valued functions, i.e. taking values in \mathbb{R}^m .

dot product can be reformulated as a matrix product.

$$\nabla f(\vec{x}_0) \cdot \vec{h} = \begin{pmatrix} \partial_1 f(\vec{x}_0) & \dots & \partial_n f(\vec{x}_0) \end{pmatrix}_{1 \times n} \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix}_{n \times 1}$$

Definition: Let $\vec{f}: U \rightarrow \mathbb{R}^m$ be defined on an open set $U \subseteq \mathbb{R}^n$. Let $\vec{x}_0 \in U$. We say that \vec{f} is differentiable at \vec{x}_0 if there is a linear map $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ (given by $m \times n$ matrix) and a function $\vec{\varepsilon}: B(r, \vec{0}) \rightarrow \mathbb{R}^m$ defined on some ball with small enough radius $r > 0$ s.t.

$m \times 1$ column vectors \hookrightarrow
$$\vec{f}(\vec{x}_0 + \vec{h}) = \vec{f}(\vec{x}_0) + \underbrace{A}_{m \times n} \underbrace{\vec{h}}_{n \times 1} + |\vec{h}| \vec{\varepsilon}(\vec{h}) \quad (*)$$

for all $\vec{h} \in B(r, \vec{0})$ and $\lim_{\vec{h} \rightarrow \vec{0}} \vec{\varepsilon}(\vec{h}) = \vec{0}$.

Proposition: \vec{f} as in the definition is differentiable at \vec{x}_0 iff each component function $(f_i: U \rightarrow \mathbb{R})$ is diffable for $i = 1, \dots, m$.

Moreover, A is the jacobian matrix:

$$A = \left(\partial_j f_i(\vec{x}_0) \right)_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$$

Proof: (*) is equivalent to a system of m equations

$$f_i(\vec{x}_0 + \vec{h}) = f_i(\vec{x}_0) + A_i \cdot \vec{h} + |\vec{h}| \varepsilon_i(\vec{h}) \quad i=1, 2, \dots, m$$

We need to show that $\lim_{\vec{h} \rightarrow \vec{0}} \vec{\varepsilon}(\vec{h}) = \vec{0} \Leftrightarrow \lim_{\vec{h} \rightarrow \vec{0}} \varepsilon_i(\vec{h}) = 0$ for $i=1, \dots, m$

We have \Downarrow

$$\lim_{\vec{h} \rightarrow \vec{0}} |\vec{\varepsilon}(\vec{h})| = 0$$

triangle inequality

$$|\varepsilon_i(\vec{h})| \leq |\vec{\varepsilon}(\vec{h})| \leq \sum_{i=1}^n |\varepsilon_i(\vec{h})|$$

$$\downarrow \quad \quad \downarrow \quad \quad \downarrow$$

$$0 \quad \quad \leftarrow 0 \quad \quad \leftarrow 0$$

We have already shown that if f_i is differentiable at \vec{x}_0 then

$$A_i = \nabla f_i(\vec{x}_0).$$

■

Definition If $\vec{f}: U \rightarrow \mathbb{R}^m$ is differentiable at \vec{x}_0 we call

$$\left(\partial_j f_i(\vec{x}_0) \right)_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}} = D\vec{f}(\vec{x}_0)$$

The derivative of \vec{f} at \vec{x}_0 .

(if $m=n=1$, $f: U \subset \mathbb{R} \rightarrow \mathbb{R}$ $Df(x_0) = (f'(x_0))$ 1×1 matrix.)

Chain Rule (multivariable) Suppose $\vec{f}: U \subset \mathbb{R}^n \rightarrow V \subset \mathbb{R}^m$ is differentiable at $x_0 \in U$,
 $\vec{g}: V \rightarrow \mathbb{R}^p$ is differentiable at $\vec{f}(\vec{x}_0) \in V$. Then the composite function
 $\vec{g} \circ \vec{f}: U \rightarrow \mathbb{R}^p$ is differentiable at $\vec{x}_0 \in U$, and

$$D(\vec{g} \circ \vec{f})(\vec{x}_0) = D\vec{g}(\vec{f}(\vec{x}_0)) \cdot D\vec{f}(\vec{x}_0)$$

$$\begin{matrix} p \times m & \uparrow & m \times n \\ & \text{matrix product.} & \end{matrix}$$

If we denote the coordinates of \mathbb{R}^n by (x_1, \dots, x_n)

" " \mathbb{R}^m by (y_1, \dots, y_m)

" " \mathbb{R}^p by (z_1, \dots, z_p)

then $\vec{y} = \vec{f}(\vec{x})$, $\vec{z} = \vec{g}(\vec{y})$ and

~ ~ ~

then $y = f(\bar{x})$, $\bar{z} = g(\bar{y})$ and

$$\begin{matrix} i=1, \dots, p \\ j=1, \dots, n \end{matrix} \quad \frac{\partial z_i}{\partial x_j} = \sum_{k=1}^m \frac{\partial z_i}{\partial y_k} \frac{\partial y_k}{\partial x_j}$$

$$D(g \circ f)_{i,j}$$

$$\frac{\partial z_i}{\partial x_j} = \underbrace{\left(\frac{\partial z_i}{\partial y_1}, \dots, \frac{\partial z_i}{\partial y_m} \right)}_{\substack{\text{i-th row} \\ \text{of } Dg(\bar{f}(\bar{x}_0))}} \begin{pmatrix} \frac{\partial y_1}{\partial x_j} \\ \vdots \\ \frac{\partial y_m}{\partial x_j} \end{pmatrix} \leftarrow \text{j-th column of } Df(\bar{x}_0)$$

Proof: We have $\stackrel{(1)}{f}(\bar{x}_0 + \bar{h}) = f(\bar{x}_0) + \overbrace{Df(\bar{x}_0) \cdot \bar{h} + |\bar{h}| \bar{\epsilon}(\bar{h})}^{\approx \bar{h}}$ for $\bar{h} \in B(r, \delta) \subseteq \mathbb{R}^n$
 $\stackrel{(2)}{g}(f(\bar{x}_0) + \bar{k}) = g(f(\bar{x}_0)) + Dg(f(\bar{x}_0)) \cdot \bar{k} + |\bar{k}| \bar{\gamma}(\bar{k})$ for $\bar{k} \in B(s, \delta) \subseteq \mathbb{R}^m$

Since $\lim_{\bar{h} \rightarrow \vec{0}} \bar{k} = \vec{0}$ we can find $r' \leq r$ such that $\bar{h} \in B(r', \delta) \Rightarrow \bar{k} \in B(s, \delta)$

Combining (1) and (2), we get

$$\begin{aligned} g(f(\bar{x}_0) + \bar{k}) &= g(f(\bar{x}_0)) + Dg(f(\bar{x}_0)) (Df(\bar{x}_0) \cdot \bar{h} + |\bar{h}| \bar{\epsilon}(\bar{h})) + |\bar{k}| \bar{\gamma}(\bar{k}) \\ &= g(f(\bar{x}_0)) + (Dg(f(\bar{x}_0)) Df(\bar{x}_0)) \cdot \bar{h} + \underbrace{|\bar{h}| Dg(f(\bar{x}_0)) \cdot \bar{\epsilon}(\bar{h}) + |\bar{k}| \bar{\gamma}(\bar{k})}_{\substack{\text{"?"} \\ |\bar{k}| \bar{\delta}(\bar{k}) \text{ where } \bar{\delta}(\bar{h}) \rightarrow \vec{0} \text{ as } \bar{h} \rightarrow \vec{0}}} \end{aligned}$$

It remains to show:

$$\frac{|\bar{h}| Dg(f(\bar{x}_0)) \cdot \bar{\epsilon}(\bar{h}) + |\bar{k}| \bar{\delta}(\bar{k})}{|\bar{k}|} \rightarrow \vec{0} \text{ as } \bar{h} \rightarrow \vec{0}.$$

$$\underbrace{\frac{|\bar{h}| Dg(f(\bar{x}_0)) \cdot \bar{\epsilon}(\bar{h})}{|\bar{k}|}}_{\parallel} + \underbrace{\bar{\gamma}(\bar{k})}_{\downarrow \vec{0} \text{ as } \bar{k} \rightarrow \vec{0} \text{ as } \bar{h} \rightarrow \vec{0}}$$

need to analyze

this $\frac{0}{0}$ limit