

Non-recursive DP: do base case first.

Method 3:

$(x_1, \dots, x_n)$  is a seq. of decisions:

take  $a_i, b_j$  if  $a_i = b_j$ .

remove one (which one).

$$L(i, j) = \begin{cases} 1 + L(i+1, j+1) & \text{if } a_i = b_j \\ \max\{L(i+1, j), L(i, j+1)\} & \text{if } a_i \neq b_j \end{cases}$$

$$L(n+1, j) = 0 = L(i, n+1)$$

runtime  $\Theta(n^2)$ .

Forward/Backward both work for all versions.

All-pair Shortest paths:

for every pair of nodes  $(u, v) \in V^2$  find the

shortest path from  $u$  to  $v$  in  $E$  in  $G(V, E)$  (weighted, directed).

$\forall u \in V$ , construct  $(x_1, \dots, x_k)$

Approach 1:

$X_i$  : the next node:

$\text{deg}(u) = \# \text{ choices}$

$$L(i, j) = \min \{ d(i, z) + L(z, j) : (i, z) \in E \}$$

Doesn't work bc cycles.

$L^k(i, j)$  = length of a shortest path from  $i$  to  $j$   
which has at most  $k$  intermediate nodes.

$$L^k(i, j) = \min \{ d(i, z) + L^{k-1}(z, j) : (i, z) \in E \}$$

$$L^0(i, j) = \begin{cases} 0 & \text{if } i = j \\ d(i, j) & \text{if } (i, j) \in E \\ \infty & \text{if } (i, j) \notin E \end{cases}$$

takes  $\Theta(n^4)$  time. the more parameters in  $f$  the more time it takes.

Approach 2:

$X_i$ : going thru node  $l$  or not?   
↗ enter & leave

$D^k(i, j)$  = length of shortest path from  $i$  to  $j$  w/ intermediate nodes  $\in \{1, \dots, k\}$ .

$$D^k(i, j) = \min \{ D^{k-1}(i, j), D^{k-1}(i, k) + D^{k-1}(k, j) \}$$

$$D^0(i, j) = \begin{cases} \text{weight of } (i, j) & \text{if } (i, j) \in E \\ 0 & \text{if } i = j \\ \infty & \text{otherwise} \end{cases}$$

$$\Theta(n^3)$$

goal:  $D^n(i, j)$  gives shortest distance from  $i$  to  $j$ .

Problem 3 on HW:

Path( $k, i, j$ ) should have no loops.